

Cover Memo

File #: CONS 21-636, Version: 1

DATE: December 7, 2021

TO: Mayor and City Council

FROM: **Development Services Director** 

## **SUBJECT**

Approval of Final Map of Tract 8359, a 13 Lot Subdivision at 24765 Hesperian Boulevard, Hayward to Allow the Construction of Single-Family Residences with Common Open Space Area, and Related Site Improvements; Applicant/Owner: Jason Creek Ventures, LLC., Application No. 202101368

## RECOMMENDATION

That the Council adopts the attached resolution (Attachment II) to approve the Final Map for Tract 8359 (Attachment III), find it in substantial conformance with the approved Vesting Tentative Tract Map (Attachment IV), and authorize the City Manager to execute the Subdivision Agreement, related other documents and take appropriate administrative actions to effectuate the improvements required by the Conditions of Approval.

## **SUMMARY**

The Final Map for Tract 8359 subdivides one existing parcel at 24765 Hesperian Boulevard into 13 lots consisting of 13 single family homes and six accessory dwelling units, a common open space, and related site improvements. A Vicinity Map is included as Attachment V. The Council is also requested to authorize the City Manager to execute a Subdivision Improvement Agreement to compete all required improvements.

The Final Map and Improvement Plans are based on the Vesting Tentative Map approved by Council by Resolution 18-117 on June 19, 2018. In addition to the Vesting Tentative Map, Council approved Ordinance 18-08 on June 19, 2018, rezoning the property to a Planned Development District. The City Engineer has reviewed the Final Map and Improvement Plans and has determined these documents to be in substantial compliance with the City approved Vesting Tentative map, applicable City Standards and addressing the City's conditions of map approval.

## **ATTACHMENTS**

Attachment I	Staff Report Tract 8359
Attachment II	Resolution Tract 8359
Attachment III	Final Map Tract 8359
Attachment IV	Vesting Tentative Map Tract 8359
Attachment V	Vicinity Map